

A numerical approach for the determination of the primary fabric of granular soils

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Abstract. Granular soil as a porous medium consists of particles, touching each other and forming a solid skeleton with interconnected pores. The transfer of externally applied loads is in most cases not homogeneous, but takes place mostly in a limited number of particles creating so-called force chains. The assembly of force chains is frequently referred to the primary fabric of a soil. The knowledge of the primary fabric is of vital importance for the analysis of many soil behaviours as, for instance, in the assessment of suffusion. Most of the current numerical models, mostly based on a discrete element approach, generate an artificial soil specimen by creating particles randomly. Therefore, particle position is not under control at all, and as a consequence the influence from particle arrangement on the creation of the primary fabric is neglected. This paper presents a sequential packing method, which allows studying two different types of particle arrangements for a given and constant grain size distribution: (1) layer-wise, producing a layered structure and (2) discrete, leading to a rather homogeneous soil structure. The generated soil specimens are compacted using a discrete element model under oedometric boundary conditions and zero gravity to create force chains within the soil structure. These force chains are then analysed to determine the soil fraction contributing to the load transfer. The results of the study provide an evidence of the influence of the particle arrangements on the appearance of the soil skeleton and the fraction of particles involved.

Introduction

Soil is not only the most popular material for hydraulic structures, such as embankment dams; it is also the foundation for most civil engineering structures. Organic free soil, as a typical porous medium, consists of solid particles and pores filled with water and air. In granular soils generally only the particles take over and transfer the externally applied load. However, the contribution of each particle in the load transfer varies. Particularly in well graded soils, coarse particles are often in contact with many other particles creating *force chains*, which means a chain of particles transferring the load from one end of the specimen to the other. Particles included in these force chains are kept firmly in their position and form the soil *primary fabric* (PF) [4] which is also referred to as the *soil skeleton*. Otherwise, the fraction of fine particles fills the pores created by the PF. These particles can be referred to as *loose particles* (LP), which are kept in the pores of the PF and support only the weight of other fine particles above (Fig. 1).

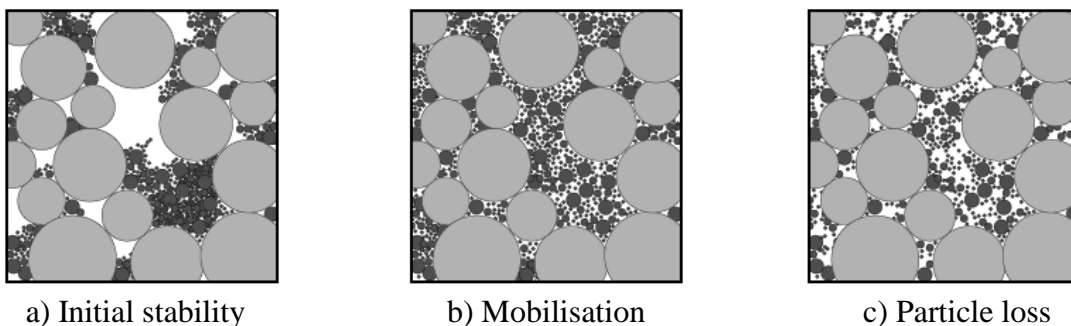


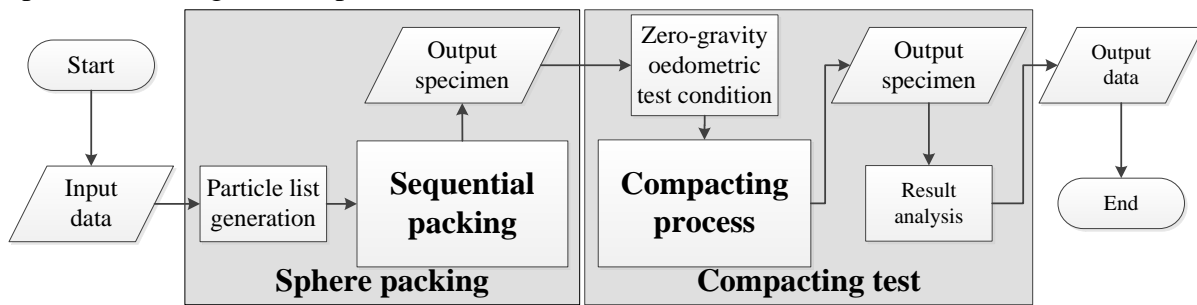
Fig. 1 PF (coarse grey particles) and LP (fine black particles) in suffusion process [9]

1 The determination of the PF, as well as the determination of LP, is of vital importance for many
 2 soil behaviour analyses such as load distribution and internal stability. Commonly, it is not known
 3 which fraction of the soil contributes to the PF. However, it allows applying filtration studies and
 4 filter criteria for example for the assessment of suffusion, when the PF, playing the role of filter, and
 5 LP, playing the role of base, are separated clearly [3, 8]. Nonetheless, there are not many methods
 6 available for the differentiation of PF and LP. An empirically derived method determines the
 7 minimum PF mass by an average void ratio of the PF, e_p , and porosity of LP, n_l [4]. Another recent
 8 study suggested a calculation of the maximum LP mass by LP porosity, density and PF volume [3]. In
 9 both methods, the determination of the input parameters is not clear, which hinders a practical use.

10 This paper provides a numerical approach for determining the PF of a given grain size distribution
 11 by number of particles and mass fraction. Moreover, calculation results highlight the impracticability
 12 of an assumption of a sharp transition between filter and base referred to as delimiting point [3], or
 13 inflection point [6]. The paper also contributes a novel study on the influence of particles arrangement
 14 on the resulting PF, which is often overlooked in empirical studies [11].

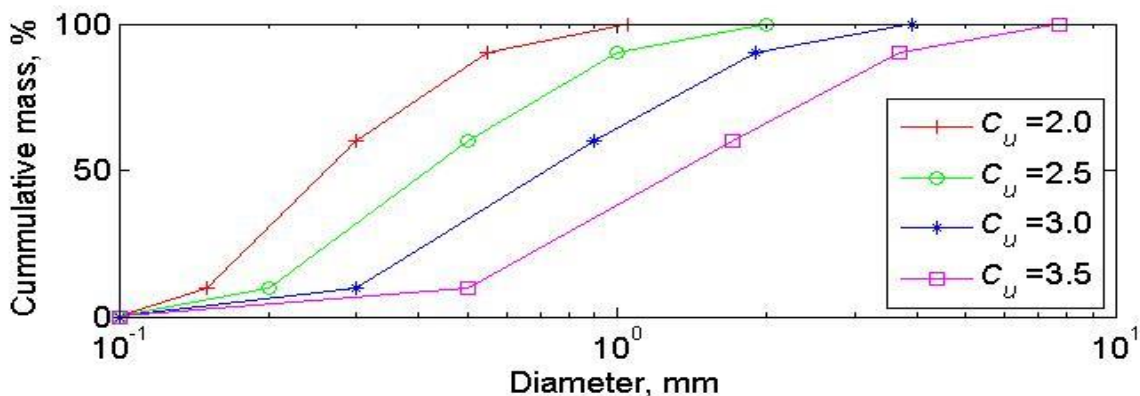
15 2. Simulation algorithm

16 While many similar researches are based on commercial software tools such as PFC3D [5, 7], the
 17 numerical simulation presented here was developed as an authorial open source code, which is built in
 18 C++ using the Mechsys library [1], developed partly by the authors as well. This code can be
 19 optimized during the compilation to make the simulation much faster than usual.



20
21 **Fig. 2 Numerical approach for determining PF**

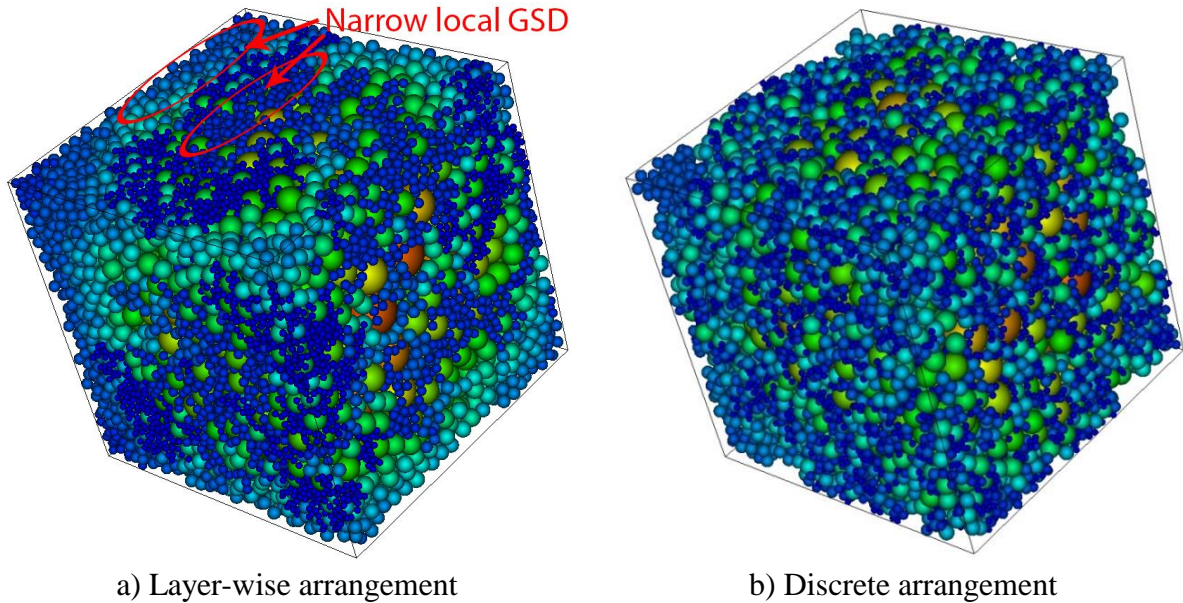
22 In the current code only spherical particles are considered due to reasons of simplicity and
 23 applicability for the calculation methods with the aim of modelling a significant amount of particles.
 24 However, the use of particles with general shapes has been approached by the authors [2, 10] and is in
 25 principle possible for future studies. The assumption of having only spherical particles is acceptable
 26 for non-cohesive, granular soils and is frequently used by other similar researches [5, 7]. The
 27 numerical approach consists of two main parts: sphere packing and compaction test (Fig. 2).



28
29 **Fig. 3 Grain size distribution of soils used for the study**

30 Regarding the first part, a list of particles are generated before the sequential packing process
 31 according to the grain size distribution (GSD), the predefined volume of specimen and its porosity.

1 All generated specimens have the same porosity, $n = 0.35$, and the coefficient of uniform, C_u , is varied
2 from 2.0 to 3.5 (Fig 3). The soils with $C_u < 3$ are considered as *narrow-graded* (NG) soils, and the rest
3 is classified as *wide-graded* (WG) soils according to [4]. The GSD is divided into 20 intervals of 5%
4 by mass. Each interval defines a mean diameter set to all particles in the given interval. Although this
5 division reduces the ratio d_{\max}/d_{\min} at some level, it does not influence much the GSD. The number of
6 particles must be an integer number. Abundant mass of a coarse interval is therefore transferred to the
7 next finer interval.



8 **Fig. 4 Particle arrangements studied in the simulation**

9 In most of the prior, similar numerical models, particles are generated randomly [5-7] hence, the
10 particles arrangement was not controlled and, therefore, neglected. The presented approach employed
11 a sequential packing algorithm, which has a better particle position control. Four particles are added
12 first to build a tetrahedron with 4 faces, each of which consists of three particles. Afterthat, another
13 particle is adjusted to one face to build a new tetrahedron with three new faces. The process is
14 repeated until the moment when all particles are packed. If the particles are added by descending order
15 of size, the soil specimen will tend to create a *layer-wise arrangement* (LA), where the neighbouring
16 particles have similar sizes (Fig. 4a). Otherwise, when the fine particles have priority to be put
17 between the coarse particles, the specimen shows a *discrete arrangement* (DA), which is more
18 homogenous in comparison with the LA (Fig. 4b). Moreover, this semi-analytical method for sphere
19 packings takes only just over 20 minutes of calculation with a singular computational core 2.7 GHz
20 for 77000 particles. More details of the sequential packing algorithm can be found in [11].

21 In the second part of the simulation, the visual oedometric test and zero gravity conditions are
22 applied by the DEM model (Fig. 5). The parameters of the DEM simulation are represented in Table
23 1. Since it is difficult for the determination of the PF to separate forces created by self-weight of
24 particles and created by external load, all particles are set to be free from gravity. As a result, only
25 particles belonging to the PF are kept firmly within particle chains, crossing each other, and have at
26 least four contacts with other particles and/or boundary walls.

27
28 The line called *force chain* connects the centres of particles in a chain and represents the *normal*
29 *contact force* (NCF) acting between them. Their magnitude are visualised in Fig. 6 by its thickness
30 and colour. Because the paper focus only on the primary friction determination, the tangential
31 contact forces are not illustrated. Meanwhile, the LP tend to have no contact forces because the NCF
32 of the PF pushes them out of their position. The force chain data are then analysed by a Matlab code to
33 identify PF and LP of the soil specimen.

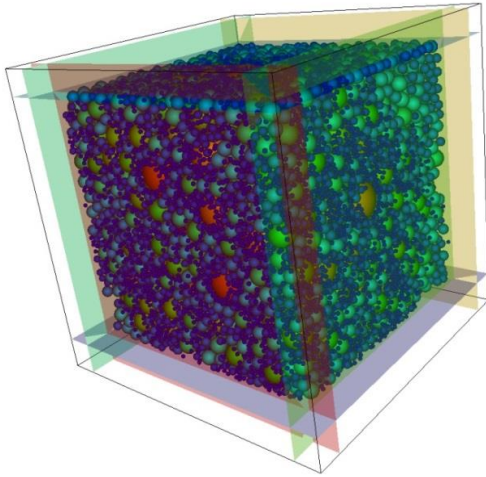
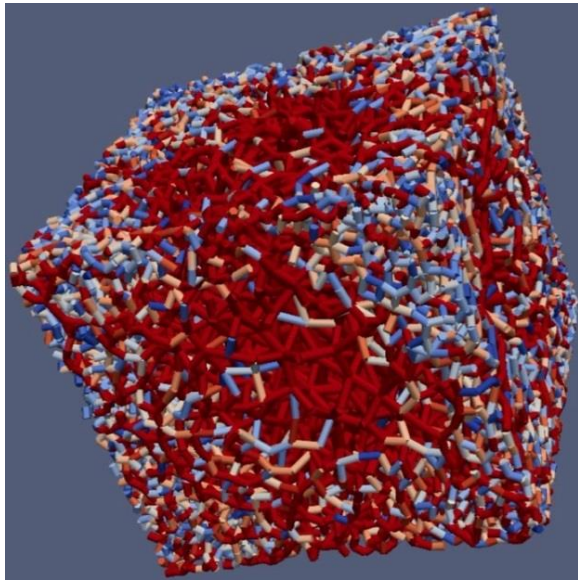


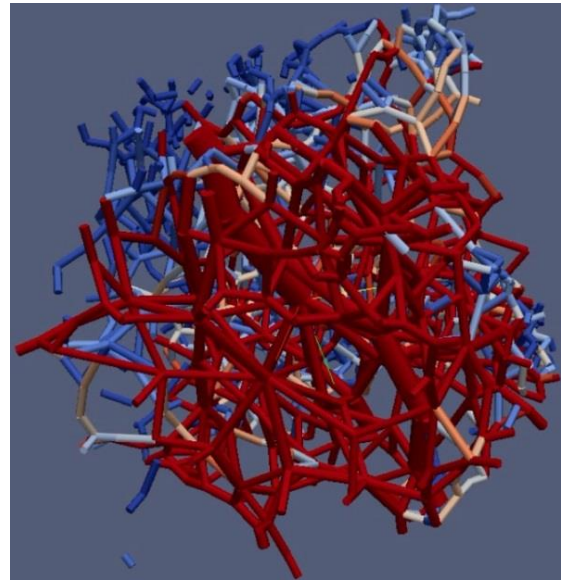
Fig. 5 Oedometric boundary conditions for the DEM test

Table 1. DEM simulation parameters

Parameters	Value
Gravity constant, g [m/s^2]	0
Normal stiffness, K_n [N/m]	$2.0 \cdot 10^7$
Tangential stiffness, K_t [N/m]	$2.0 \cdot 10^7$
Normal viscous coefficient, G_n [s^{-1}]	$1.6 \cdot 10^4$
Tangential viscous coefficient, G_t [s^{-1}]	$0.8 \cdot 10^4$
Time step, dt [s]	$3.2 \cdot 10^{-10}$
Intermediate output time, d_{out} [s]	$3.2 \cdot 10^{-4}$
Total time of simulation, t_f [s]	$1.2 \cdot 10^{-2}$
Limit Kinematic energy, K [Nm]	10^{-7}
Rolling stiffness coefficient, β	0.12
Plastic moment coefficient, η	1.0



a) Narrow-graded, layer-wise arrangement



b) wide-graded, discrete arrangement

Fig. 6 Force chains under oedometric load and zero gravity

1

2 3. Results and discussion

3 There is an obvious trend that narrow-graded, LA soils involve more particles in their PF, which
 4 lead to a bigger proportion by number, as well as by mass, of PF (Fig. 7, Fig. 8). The immediate reason
 5 of this trend is that a particle in LA often has the similar size to its neighbours, which makes the local
 6 GSD narrower than the global GSD. Meanwhile, because the fine and coarse particles are put nearby
 7 in LA, the local GSD turns to a gap-graded one.

8 The phenomenon is severe for the narrow-graded soils, where the PF involves a double amount of
 9 particles with LA in comparison with DA (Fig. 7). In this case, the load applied to the soils with LA
 10 are better distributed in a denser particle network. However, when the GSD spreads widely enough,
 11 but is still divided into only 20 intervals, the difference between the mean sizes of close intervals
 12 becomes significant, which makes the influence of the particle arrangement less severe. This
 13 influence of the gap-graded gradation is demonstrated vividly by the test results of the soils with
 14 $C_u=3.5$ (Fig. 7, Fig. 8).

15 The LA has a practical meaning, that it simulates real soil dumped from trucks on construction
 16 sites: coarse particles drop faster and farther, while fine particles take more time for the slide and the
 17 suspension before they settle. However, the results are not implying that the segregated soil is

1 practically more secure than the homogeneous soil. When the new mass of soil is dumped on the
 2 previous mass, the coarse particles may come in contact directly with the prior fine particles. As a
 3 consequence, the local narrow-graded GSD might turn to a gap-graded one.

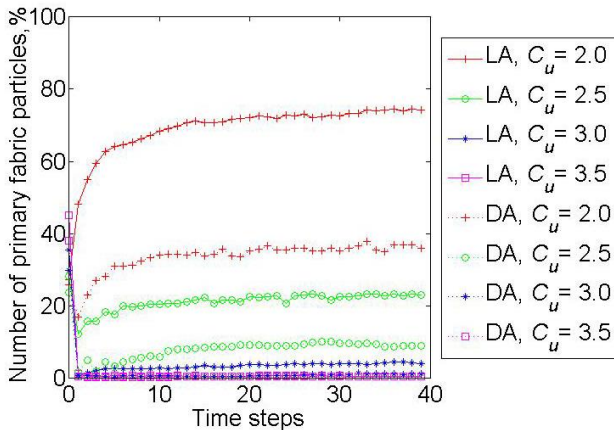


Fig. 7 Proportion by number of primary fabric particles

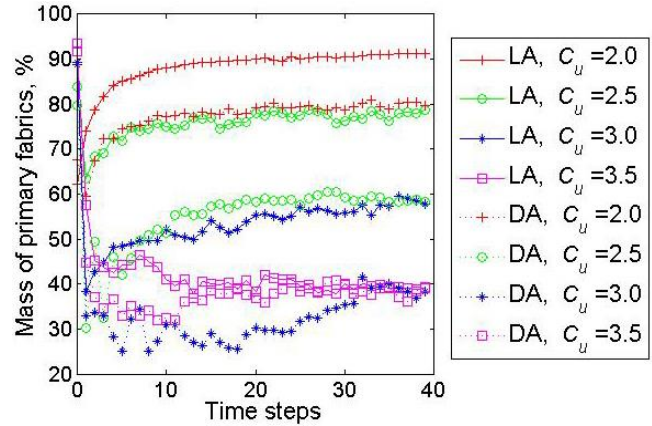


Fig. 8 Proportion by mass of primary fabrics

4 The quantitative results show that the PF of the wide-graded soils may take only just over 2% by
 5 number of particles (Fig. 7), but it contributes just under 40% by mass (Fig. 8). This fact is contrary to
 6 previous empirical estimates that LP in wide-graded soils takes less than 20% of the total soil mass
 7 [4]. The study conducted by [4] is based on the common assumption that the GSD of soil can be cut
 8 into two parts by a delimiting value. All particles smaller than that value are considered being
 9 attributed to LP and vice versa. This assumption of having a sharp delimiting value was also used by
 10 sequential empirical studies [3, 8] mainly due to the significant challenge to determine empirically the
 11 load distribution on each soil particle.

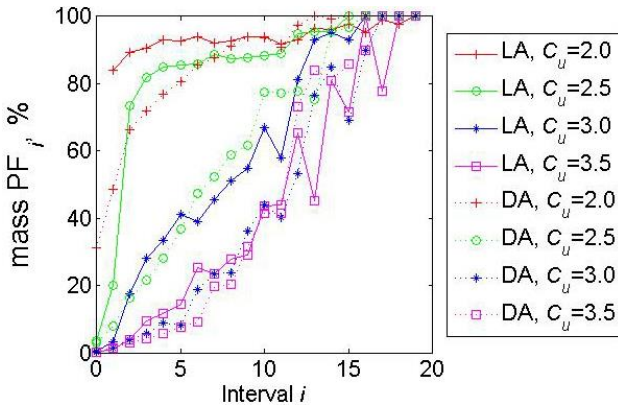


Fig. 9 Contribution to primary fabric in each intervals

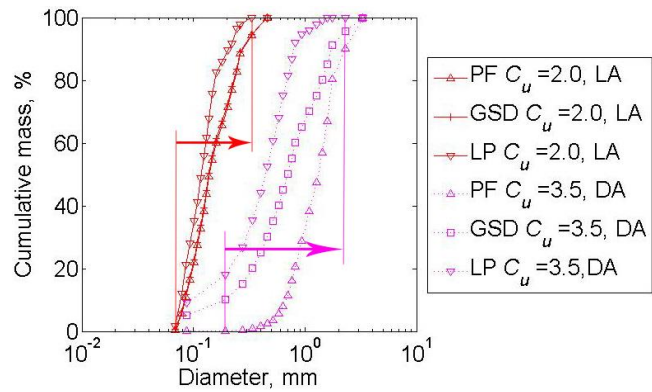


Fig. 10 Overlapping zone between primary fabric and loose particles

12 Nevertheless, the numerical force chain analysis is able to identify the stress state of all particles,
 13 which shows that most of the intervals of a given GSD contribute, to some extent, to both LP and PF
 14 (Fig. 9). The *overlapping zone* between PF and LP in GSD in both narrow and wide-graded soils
 15 cannot be overlooked because of its wide range (Fig. 10) of more than 60% of the soil mass (Fig. 9). A
 16 note should be left here that there are always some fine particle kept accidentally in the force chains,
 17 therefore, the OZ is considered to start from more than 1% of the PF mass (Fig. 10).

18 4. Conclusion

19 By way of conclusion, the simulation is able to determine soil PF and LP, which is important for
 20 many soil behaviour analyses. In addition, the results of the study highlight that there is no sharp
 21 boundary between PF and LP in the soil GSD. The approaches based on the assumption of that sharp

1 boundary [3, 4, 8] might be applicable, but they consequently neglect the important phenomenon of
2 having an overlapping zone between PF and LP.

3 In addition, the simulation also provides a key understanding about the influence of the particle
4 arrangement on the development of the PF and its behaviour under load. This is one important
5 characteristic of a soil, which was often overlooked and neglected in prior empirical studies [12].

6 The future work aims to involve seepage flow into the simulation to have a precise view on the
7 detachment of soil particles from the PF.

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